

# THE DESIGN CHALLENGE

Make the protocol loop around frequency high enough for real-time control – and still play by the rules!

**27 MHz • HALF-DUPLEX • DIGITAL**

CONTROL VALUES TO SUBMARINE

PROCESS VALUES TO SHORE

ONE CHANNEL,  
TWO DIRECTIONS,  
ONE CHALLENGE!

THE BALANCE  
MAKES IT WORK!

STAY WITHIN  
THE RULES

- 10 kHz channel spacing
- Max duty cycle
- Out-of-band emissions
- Fair use, no interference

I NEED SPEED!

FOLLOW THE RULES!

HIGH LOOP RATE  
FOR REAL-TIME CONTROL

- Fast update rate
- Low latency
- Reliable control
- Smooth operation

WHAT SLOWS THE LOOP?



Slow processing



Long packet or overhead



Collisions & retries



Noise & fading



Low power margin



PROTOCOL LOOP  
AROUND FREQUENCY

TOO SLOW JUST RIGHT! TOO SLOW

WHAT BREAKS THE RULES?



Too much transmit time



Too wide spectrum



Interference with others



Exceeding power limits



Non-compliant operation



THE GOAL: FAST, RELIABLE, AND COMPLIANT COMMUNICATION.  
REAL-TIME CONTROL – RESPONSIBLE USE.

HAPPY SUB,  
HAPPY OPERATOR,  
HAPPY SPECTRUM!

